# The IEEE 33 Bus Distribution System Load Flow Analysis Using Newton Raphson Method

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Abstract—In this paper, the IEEE Bus Distribution System load flow analysis using Raphson is Newton method presented. Fundamental equations for load flow analysis of n-bus system are presented along with the algorithm for Newton Raphson load flow analysis and the case study IEEE 33-Bus System dataset. Then, Newton Raphson load flow MATLAB program was developed and used to determine the bus voltages and phase angles at each bus of the case study IEEE 33 bus system. With Newton Raphson method, convergence occurred at the 4th iteration. The results also show that only four buses (namely, bus 1,2, 19 and 20) out of the 33 buses have voltages that satisfy the acceptable voltage level of 95% or 0.95 p.u. The rest of the buses have voltage values that are below the acceptable value. The result presented in this paper is relevant for evaluating the stability of the power system. With most of the bus voltages below the acceptable minimum value, it calls for voltage profile enhancement on the bus system

Keywords— IEEE 33 Bus Distribution System, Bus Voltage, Load Flow Analysis, Phase Angle, Newton Raphson Method

#### **1.0 Introduction**

Successful deployment and sustenance of power system network require proper planning and design. Particularly, there is need to determine the present and future load demand and design the power network for such know and expected future load profile [1,2,34,5,6,7,8]. However, even when such measures are taken, load flow analysis is required to understand voltage profiles on the buses and to ensure that the voltages are within the acceptable range for proper functioning of the power network [9,10,11,12,13,14].

Also, in some power networks, distributed generating technique is adopted [15,16,17,18]. In such case, different

power generators ranging from hydro, solar, wind, fossil fuel-based options are incorporated into the power source mix [ 19,20, 21,22, 23,24, 25,26, 27,28, 29,30, 31,32, 33,34,35, 36,37, 38,39, 40,41, 42,43, 44,45]. Again, load flow analysis is required to ascertain the stability of the power system when the distributed generating solution is adopted [46,47]. Also, overloading and unbalanced loads in the power network can cause problems in the network. Load flow analysis will help the power system engineer to simulate such scenarios and evaluate their impact on the power network.

Notably, load flow analysis can be performed using different iterative methods as well as using data-driven models. One of the iterative solution is the Newton Raphson method which has been widely applied in diverse areas and has performed better than some other contending iterative algorithms [48,49,50,51,52,53,54,55,56,57,58,59,60,61]. As such, this paper presents load flow analysis on a case study IEEE 33 Bus Distribution System using Newton Raphson (NR) method [62,63,64]. The detailed mathematical models for the NR iterative load flow solution are presented along with the NR load flow analysis procedure. Specifically, the analysis in this paper yielded the voltage and phase angles at each bus of the case study IEEE 33 bus system. The resulting voltage and phase angle profile are used to assess the voltage and power stability of the case study bus

## 2.0 Methodology

network.

#### 2.1 Derivation of Fundamental Equations for Load Flow Analysis of N-bus System

Consider an n-bus system comprising of voltages, admittances and line real and reactive power flows between pairs of buses indexed at say i, k; then the real and reactive power can be deduced by taking into consideration the current flowing into bus i for an N-bus network.

The current received at bus i from the generator or power grid is given as;

$$I_{i} = Y_{i1} V_{1} + Y_{i2} V_{2} + \ldots + Y_{ik} = {}^{n} {}_{ik=1} Y_{ik} V_{k}$$
(1)

(1)

Considering magnitude and phase angle, the voltage and admittance will be given as:

$$V_k = V_K \angle \delta_k$$
 (voltage at the bus k) (2)

$$Y_{ik} = Y_{ik} \angle \theta_{ik}$$
 (admittance between bus i and bus k)  
(3)

Substitute Equation 2 and Equation 3 into Equations 1 gives  $I_i = {}^n_{ik=1} Y_{ik} \angle \theta_{ik} \quad V_k \angle \delta_k \quad (4)$ 

where  $\delta i$ ,  $\delta k$  are phase angles of bus i and k, while  $\delta_{ik}$ is the angular difference between bus i and k. The conjugate of the injected current at bus i will be;

$$I_{i^{*}} = {}^{n}{}_{ik=1} Y_{ik} \angle -\theta_{ik} V_{k} \angle -\delta_{k}$$
(5)  
The apparent power available at bus i will be;

$$S_i^* = V_i I_i = P_i + j Q_i \qquad (6)$$

where  $P_i$  and  $Q_i$  denote its real and reactive powers Substituting Equation 5 into Equation 6, considering the magnitude and angle gives:

$$P_i + jQ_i = V_i \angle \delta_{i\,i,=1} Y_{ik} \angle -\theta_{ik} V_k \angle -\delta_k \quad (7)$$
  
Rearranging Equation 7 gives;

$$P_i + jQ_i = {}_{i,=1}Y_{ik}V_iV_k \angle (-\theta_{ik} + \delta_i - \delta_k)$$
(8)  
However,

$$\delta_{ik} = \delta_i - \delta_k \tag{9}$$

(The angle difference is defined by  $\delta ik = \delta i - \delta k$ .)  $-\boldsymbol{\theta}_{ik} = \boldsymbol{\theta}_{ik}$ (10)

$$P_{i+j}Q_{i} = {}^{n}{}_{i,=1} Y_{ik}V_{i}V_{k} \angle(\theta_{ki} + \delta_{ik})$$
(11)  
From the (11, the active real and imaginary power will be;

$$P_{i} = {}^{n}_{i-1} Y_{ik} V_{i} V_{k} \cos(\theta_{ki} + \delta_{ik})$$
(12)

$$Q_{i} = {}^{n}_{i=1} Y_{ik} V_{i} V_{k} \sin(\theta_{ki} + \delta_{ik})$$
(13)

Equation 12 and Equation 13 are used to obtain calculated values of real and reactive power. Note that when the bus generates electrical power, it is termed a generator bus otherwise it is a load-bus; a slack bus is also often necessary to accommodate (suck-up) the excess power flows.

The line flows may further be expressed as changes in the computed real bus/or generator powers with respect to prespecified real bus/or generator values and is expressed as:

$$\Delta P_i = P_i {}^{sp} - P_i {}^{cal} \tag{14}$$

Where  $P_i^{sp}$  = the specified real bus powers at power exchange sequence,  $P_i^{cal}$  = the computed real bus powers at power exchange sequence i, using Equation 12. Similarly, the reactive power changes may be expressed as:

$$\Delta Q_i = Q_i^{sp} - Q_i^{cal}$$
(15)

Where  $Q_i^{sp}$  = the specified reactive bus powers at power exchange sequence i,  $Q_i^{cal}$  = the computed reactive bus powers at power exchange sequence i, using Equation 13. Typically, the admittances, line power demand and generations are given while the bus voltages and angles are obtained by making an initial guess and solving using a load-flow program. The net power balance is then expressed as the sum over all bus power sequence exchanges as:

$$\Delta P_{net} = {}^{n}{}_{i} \Delta P^{2}{}_{i} \qquad (16)$$

And,

$$\Delta Q^{net} = {}^n{}_i \Delta Q^2{}_i \tag{17}$$

Working data was obtained for the three feeders considered from IEEE 33 bus system as regards transformer and feeder parameters. Based on the acquired data, calculations were done using per unit system to get the MVAs for easy representation of the system schematic diagram. Let the base MVA be 100 for a per unit voltage of unity, knowing that:

$$Z_{p.(new)} = Z_{p.u(old)} \times \frac{MVA_{new}}{MVA_{old}}$$
(18)

$$Z_{1new} = 0.1217 \times \frac{100}{30} = 0.3651p. u$$
 (19)

$$Z_{2new} = 0.1028 \times \frac{100}{60} = 0.1542p. \ u \tag{20}$$

Transformer  $1(T_1)$  and Transformer 2 (T<sub>2</sub>) are connected in parallel and as such their equivalent impedance will be gotten using Equation 8.

$$Z_{p.uequi} = \frac{z_{1p.u} \times z_{2p.u}}{z_{1p.u} + z_{2p.u}}$$
(21)

$$Z_{p.uequi} = \frac{0.3651 \times 0.1542}{0.3651 + 0.1542} = 0.1084p. u$$
(22)

we proceeds from substituting values into Then Equation 18, Equation 19 and Equation 20, this is used for the network schematic shown in Figure 1, which is a IEEE 33 bus system comprising of a grid, distribution lines, high voltage circuit breakers and lumped loads representing feeder loads.

#### 2.2 Load Newton Raphson Flow Analysis Procedure and the case study IEEE 33-Bus System

The load flow analysis using Newton Raphson method can be implemented using the following procedure;

STEP 1: Select the error tolerance value,  $\varepsilon$  and initialise the iteration counter k = 0

STEP 2: Read the load flow dataset and formulate the  $Y_{ii}$ nodal admittance

STEP 3: Choose the initial bus voltage values (where the voltage,  $V_i$  magnitude is  $|V_i|^k$  and the voltage,  $V_i$ phase angle is  $\delta_i^{k}$  and the n bus is set as the reference bus, where;

 $V_i = V_{i,spec} < 0^\circ$  for all the PV buses  $V_i = 1 < 0^\circ$  for all the PQ buses

STEP 4: At the k+1 iteration, by using  $V_i^k$  the values of  $P_i^{k+1}$  (the real power) are computed for all the PV buses using the equation given as;  $P_i$ , ca

$$u^{k+1} = P_i = G_{ii} |V_i|^2 + \sum_{j=1}^n (|V_i| |V_j| (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}))$$

Where  $\theta_{ij} = \theta_i - \theta_j$  is the difference in the angle between bus *i* and bus j while  $G_{ij}$  and  $B_{ij}$  denote to conductance and the susceptance of the bus system respectively.

STEP 5: At the k+1 iteration, by using  $V_i^k$  the values of  $Q_i^{k+1}$  (the reactive power) are computed for all the PQ buses using the equation given as;  $cal^{k+1} = 0, = -B_{u}|V_{u}|^{2}$  $Q_i, cal^{k+1} = O_i =$ 

$$P^{k+1} = Q_i = -B_{ii}|V_i|^2 + \sum_{j=1}^n (|V_i||V_j|(G_{ij}\sin\theta_{ij} - B_{ij}\cos\theta_{ij}))$$

- STEP 6: By using  $V_i^k$  along with its elements spread over the H, N, K and L submatrices form the Jacobian matrix  $[J^k]$ .
- STEP 7: Compute  $\Delta P_i$  and  $\Delta Q_i$  (which are the active and reactive power differences or mismatches respectively, for I = 1, 2, 3, ..., n-1 where  $\Lambda P_i^k = P_i$  $-P_{k} cal^{k+1}$

$$\Delta Q_i^{\ k} = Q_{i,spec} - Q_i, cal^{k+1}$$

STEP 8: Compute  
$$\begin{bmatrix} \Delta \delta_i^k \\ \Delta \nu^k \\ \frac{\Delta \nu^k}{\nu} \end{bmatrix} = [J^k]^{-1} \begin{bmatrix} \Delta P_i^k \\ \Delta Q_i^k \end{bmatrix}$$

STEP 9: Re-compute the values for V<sub>i</sub> and  $\delta_i$  as follows;  $\delta_i^{k+1} = \delta_i^k + \Delta \delta_i^k$   $V_i^{k+1} = V_i^k + \Delta V_i^k$ STEP 10: Stop the Newton Raphson iteration when all the

values obtained for  $\Delta P_i$  and  $\Delta Q_i$  are less or equal

to  $\varepsilon$  otherwise increase the iteration counter k by 1 and go to Step 4 and continue with the iteration The IEEE 33 bus system is a standard test bus with generator buses, load buses and interconnected lines. In this paper, Bus 1 in the case study IEEE 33 bus system is selected as the slack bus. An interconnected bus line of the IEEE 33 bus system is shown in Figure 1. The line data and the bus data for the IEEE 33 bus system used for the study are given in Table 1.



Figure 1: The IEEE 33 bus system extracted from Etap software

The IEEE 33 bus system line dataset						The IF	EEE 33 bus s	ystem bus	dataset
Bus Number	Sending Bus Number	Receiving Bus Number	Line Resistance	Line Reactance		Bus Number	LOAD: Active Power (KW)	LOAD : Reactive Power (KVAR)	Q Injected
1	1	2	0.0922	0.047		1	0	0	0
2	2	3	0.493	0.2511		2	100	60	0
3	3	4	0.366	0.1864		3	90	40	0
4	4	5	0.3811	0.1941		4	120	80	0
4	5	6	0.819	0.707		5	60	30	0
6	6	7	0.1872	0.6188	]	6	60	20	0
7	7	8	0.7114	0.2351	]	7	200	100	0
8	8	9	1.03	0.74		8	200	100	0

Table 1 The IEEE 33 bus system line dataset and bus dataset

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9	9	10	1.044	0.74
10	10	11	0.1966	0.065
11	11	12	0.3744	0.1238
12	12	13	1.468	1.155
13	13	14	0.5416	0.7129
14	14	15	0.591	0.526
15	15	16	0.7463	0.545
16	16	17	1.289	1.721
17	17	18	0.732	0.574
18	2	19	0.164	0.1565
19	19	20	1.5042	1.3554
20	20	21	0.4095	0.4784
21	21	22	0.7089	0.9373
22	3	23	0.4512	0.3083
23	23	24	0.898	0.7091
24	24	25	0.896	0.7011
25	6	26	0.203	0.1034
26	26	27	0.2842	0.1447
27	27	28	1.059	0.9337
28	28	29	0.8042	0.7006
29	29	30	0.5075	0.2585
30	30	31	0.9744	0.963
31	31	32	0.3105	0.3619
32	32	33	0.341	0.5302

## 3. Results and discussion

The focus of this paper is to use MATLAB program to determine the bus voltages and phase angles at each bus for the IEEE 33 bus system. With Newton Raphson method, the solution converged at the 4<sup>th</sup> iteration. The result obtained from the MATLAB program for the bus voltage and phase angle based on the Newton Raphson load flow method are given in Table 2. Specifically, Figure 2 shows the scatter plot of the bus voltage value for each bus using

Newton Raphson method is presented in Figure 2 while Figure 3 shows the bar chart of the bus voltage value for each bus using Newton Raphson method. Based on the bar chart of Figure 3, only four buses (namely, bus 1,2, 19 and 20) have voltages that satisfy the acceptable voltage level of 95% or 0.95 p.u. The rest of the buses have voltage values that are below the acceptable value. Also, Figure 4 shows the scatter plot of the phase angle value for each bus using Newton Raphson method

Bus No	Voltage (p.u.)	Phase Angle (radians)		
1	1.0000	0.0000		
2	0.9862	0.0116		
3	0.9270	0.0743		
4	0.8924	0.1218		
5	0.8607	0.1739		
6	0.7693	0.2954		
7	0.7277	0.3218		
8	0.7236	0.3904		
9	0.7036	0.4948		
10	0.6954	0.5951		
11	0.6981	0.6094		
12	0.7032	0.6330		
13	0.7077	0.7334		
14	0.7053	0.7737		
15	0.7085	0.8019		
16	0.7135	0.8253		
17	0.7150	0.8631		
18	0.7170	0.8706		
19	0.9821	0.0116		
20	0.9543	0.0124		
21	0.9486	0.0118		
22	0.9432	0.0110		
23	0.9198	0.0769		
24	0.9094	0.0800		
25	0.9042	0.0814		
26	0.7635	0.3074		
27	0.7568	0.3226		
28	0.7226	0.3739		
29	0.7025	0.4090		
30	0.6971	0.4272		
31	0.6815	0.4554		
32	0.6776	0.4616		
33	0.6746	0.4653		

## Table 2: The results of the bus voltage and phase angle based on the Newton Raphson load flow method







Figure 4: Phase angle of voltage values for each bus using Newton Raphson Method **4. Conclusion** 

Newton Rapson (NR) method is used to conduct load flow analysis on the IEEE 33 bus system. The NR mathematical models and algorithm are presented and the load flow program was written in MATLAB and then used to simulate the NR load flow analysis using the IEEE 33 line data and bus data. The results show that majority of the bus voltages are below the acceptable range of 0.95 p.u.

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