

Generic Finiteness of the Solutions for the Stable Cahn-Hilliard Equation with fast Growing Nonlinearity

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Abstract—Consider the Neumann boundary value problem of the stable Cahn-Hilliard equation. Under an additional condition, we prove the problem has at least one solution. Moreover, the problem has at most finite number of solutions.

Keywords—Stable Cahn-Hilliard equation; existence; generic finiteness.

1. INTRODUCTION

We consider the following problem :

$$-\Delta K(u) = g, \text{ in } \Omega \quad (1.1)$$

$$\frac{\partial u}{\partial \nu} = \frac{\partial (\Delta u)}{\partial \nu} = 0, \text{ on } \partial \Omega \quad (1.2)$$

$$m(u) = \alpha \quad (1.3)$$

Where $\alpha \in \mathbb{R}^1$ is a constant,

$$K(u) = -\Delta u + f(u) \quad (1.4)$$

$$m(u) = \frac{1}{|\Omega|} \int_{\Omega} u \, dx \quad (1.5)$$

$\Omega \subset \mathbb{R}^n (n \leq 3)$ is a bounded open domain with sufficiently regular boundary $\partial \Omega$, $f \in C^2(\mathbb{R}^1)$ is a real function which will be specified further below, ν stands for the outward normal vector on $\partial \Omega$. The problem (1.1)-(1.3) is related to the stationary state of the well-known Cahn-Hilliard equation which has been extensively studied more recently by [1-6].

In this present work we prove some general properties for this problem. These properties are helpful for us to understand the long-time dynamics of the Cahn-Hilliard equation (of course, our results are also of mathematical interests). First, we prove the existence result. Then we show a generic property of (1.1)-(1.3), i.e., for every fixed $\alpha \in \mathbb{R}^1$, we prove that there exists a dense open set G in the functional space described by g , such that for every $g \in G$, (1.1)-(1.3) has only finite solutions. The reason why we are interested in the latter problem is that, once we know that a system has at most finite stationary states, we can then give a precise description of the maximal global attractor of the system (see [5, Ch. VII]). (For the Cahn-Hilliard equation which may possess a fast growing nonlinear term f as considered here, the

existence of the maximal global attractor has just been proved recently by Li and Zhong [6].)

Throughout this paper we assume that f satisfies the following structure conditions:

F_1) $f \in C^2(\mathbb{R}^1)$, moreover, there exists a positive

constant k_1 such that

$$f(s) \geq -k_1 \quad \forall s \in \mathbb{R}^1;$$

F_2) There exists a positive constant k_2 such that

$$f'(s) \geq -k_2.$$

The Cahn-Hilliard equation arises as a model of phase transitions, Note that the typical function f arising in applications is a polynomial,

$$f(s) = \sum_{j=1}^{2p-1} a_j s^j, a_{2p-1} > 0, \quad (1.6)$$

and that this satisfies both F_1) and F_2). However, our f need not to be a polynomial function as those are considered in [1-4] and other references.

Throughout this paper, C denotes a general constant depending upon the constants that appear in F_1) - F_2), the upper bounds of $|\alpha|$ (see (1.3) for the parameter α) and other quantities such as the Sobolev embedding constants etc.

2. SOME A PRIORI ESTIMATES

In this section we establish some a priori estimates for solutions of (1.1)-(1.3). Let $(*, *)$ and $\|*\|$ denote, respectively, the inner product and norm of $L^2(\Omega)$, we define the linear operator $A = -\Delta$ with domain of definition

$$D(A) = \{ u \in H^2(\Omega), \partial u / \partial \nu = 0, \text{ on } \partial \Omega \},$$

By spectral theory we can define the spaces

$$V_s = D \left(A^{\frac{s}{2}} \right) \text{ with seminorms } |u|_s = \left| A^{\frac{s}{2}} u \right| \text{ and}$$

norms $\|u\|_s = \left(|u|_s^2 + m(u)^2 \right)^{\frac{1}{2}}$ for real s . (see [5,6],

etc.) It is well known that when $s > 0$, V_s is a

subspace of $H^s(\Omega)$ and that $\|*\|_s$ is equivalent to the

usual norm of $H^s(\Omega)$. Also, V_{-s} is the dual of V_s ,
 Moreover, for $\forall s, s' \in \mathbb{R}^1, s \leq s'$, we have the
 following Poincare-type inequality

$$|u|_s \leq \lambda_1^{-(s'-s)/2} |u|_{s'}, \forall u \in V_{s'} \quad (2.1)$$

We also denote by H the space $L^2(\Omega)$, by H and
 V_s the spaces of definitions

$$\dot{H} = \{u \in H = L^2(\Omega), m(u) = 0\}, \quad (2.2)$$

$$\dot{V}_s = \{u \in V_s, m(u) = 0\}, \quad (2.3)$$

Lemma 2.1 Assume that f satisfies $F_1), F_2)$,
 $g \in H$, then there exists a positive constant C such
 that for every solution u of (1.1)-(1.3),

$$\|u\|_1 \leq C(1+g) \quad (2.4)$$

Proof The estimate (2.4) is obtained by
 multiplying (1.1) with $A^{-1}u$ and integrating over Ω
 .The argument in detail is similar to those in Lemma 1
 of [3] and Lemma 3.1 of [5].we omit it.

Lemma 2.2 The assumptions are those in
 Lemma 2.1 ,Let u be a solution of (1.1)-(1.3),then

$$\|u\|_4 \leq C(1+g) \quad (2.5)$$

Proof We multiply (1.1) with $-K(u)$ and obtain
 (note that $\frac{\partial}{\partial v} K(u) = \frac{\partial}{\partial v} A^{-1}g = 0$ on $\partial\Omega$)

$$\begin{aligned} |K(u)|_1^2 &= -(K(u), g) = -(K(u), AA^{-1}g) \\ &\leq \frac{1}{2}|K(u)|_1^2 + \frac{1}{2}|g|_{-1}^2 \leq (\text{by(2.1)}) \\ &\leq \frac{1}{2}|K(u)|_1^2 + C|g|^2 \end{aligned}$$

Hence $|K(u)|_1 \leq |g|^2 \quad (2.6)$

Now we multiply $K(u)$ by Au and integrate over Ω
 ,by $F_2)$,we have

$$\begin{aligned} (K(u), Au) &= |u|_2^2 + \int_{\Omega} f'(u)|\nabla u|^2 dx \geq |u|_2^2 - k_2 |u|_1^2 |u|_2^2 \\ &\leq (K(u), Au) + k_2 |u|_1^2 \\ &= \int_{\Omega} \nabla K(u) \cdot \nabla u dx + k_2 |u|_1^2 \leq C(|K(u)|_1^2 + |u|_1^2) \end{aligned}$$

By (2.6) and Lemma 2.1 ,we conclude that

$$\|u\|_2 \leq C(1+g) \quad (2.7)$$

By (1.1) ,we have

$$\Delta^2 u = \Delta f(u) + g \quad (2.8)$$

Thanks to the Sobolev embedding $H^2(\Omega) \subset L^\infty(\Omega)$ ($n \leq 3$),and the estimate (2.7) ,we get

$$|u|_{L^\infty(\Omega)} \leq C \quad (2.9)$$

Since f and its derivatives f', f'' are locally
 bounded,we deduce easily from (2.7)-(2.9) that the
 estimate (2.5) holds.

Remark 2.1 When $f(s)$ is a polynomial ,

$$f(s) = \sum_{j=0}^{2p-1} a_j s^j \quad (a_{2p-1} > 0 \text{ and } g = 0, \text{ similar})$$

estimates for u are also obtained by Dlotko [3](see
 [3, Lemma 1])). However the author require that $p = 2$
 when the space dimension $n = 3$, Moreover ,our
 methods here also differ significantly from those used
 in [3].

Lemma 2.3 We assume that f satisfies $F_1)$ and
 $F_2)$, Let $G \subset H$ and $I \subset \mathbb{R}^1$ be compact ,then the set
 $U = \{u \in V_4, \exists (g, \alpha) \in G \times I \text{ such that } (u, g, \alpha)$
 satisfies (1.1)-(1.3)} is compact in V_4 .

Proof Since $H^4(\Omega) \subset C^2(\bar{\Omega})$ ($n \leq 3$),we infer
 from Lemma 2.2 that any sequence $\{u_k\} \subset U$ has a
 subsequence (still denoted by $\{u_k\}$) covering in
 $C^2(\bar{\Omega})$, Assume that

$$\Delta^2 u_k = \Delta f(u_k) + g_k \quad (2.10)$$

Where $g_k \in G$. By the compactness of $G, \{g_k\}$ has a
 subsequence $\{g_{k_j}\}$ which covers in H . Therefore
 we deduce from (2.10) that $\{u_{k_j}\}$ covering in V_4 . It is
 easily seen that the limit function of $\{u_{k_j}\}$ belonge to
 U . The proof is completed.

3. NON EMPTY AND GENERIC PROPERTIES FOR THE SOLUTION SET

For given $(g, \alpha) \in H \times \mathbb{R}^1$, we denote by
 $S(g, \alpha)$ the solution set of (1.1)~(1.3). Our aim in this
 part is two-fold. First,we prove that for every given
 $(g, \alpha) \in H \times \mathbb{R}^1, S(g, \alpha)$ is nonempty, i.e., the
 existence for (1.1)~(1.3); then we give a generic
 property for (1.1)~(1.3), move precisely, for every given
 $\alpha \in \mathbb{R}^1$, we show that there exists a dense open set
 $G \subset H$ such that for every $g \in G, S(g, \alpha)$ is finite.

Theorem 3.1 Assume that f satisfies $F_1)$ and
 $F_2)$, then $S(g, \alpha) \neq \emptyset$ for $\forall (g, \alpha) \in H \times \mathbb{R}^1$.

Proof Note that (1.1)-(1.3) is equivalent to the
 following equation:

$$A(Au + f(u + \alpha)) = g, u \in V_4 \quad (3.1)$$

Let $u \in V_2$. Since $\frac{\partial f(u + \alpha)}{\partial v} = f'(u + \alpha) \frac{\partial u}{\partial v} = 0$ on
 $\partial\Omega$, we find that $Af(u + \alpha) \in H$.

From the general theory for elliptic boundary-value problems, we deduce that there exists a unique $v \in \dot{V}_4$ satisfying

$$A^2v = -Af(u + \alpha) + g \quad (3.2)$$

Thus we can define a mapping $T : \dot{V}_2 \rightarrow \dot{V}_2$, as follows:

$$Tu = v, \forall u \in \dot{V}_2 \quad (3.3)$$

Where v is the solution of (3.2) with respect to u . It is easily seen that T is compact.

Suppose that $u \in \dot{V}_2$ satisfies: $u = \sigma Tu$ ($\sigma \in [0, 1]$), then $u \in V_4$ and satisfies

$$A(Au + f(u + \alpha)) = g \quad (3.4)$$

Where $f = \sigma f$. Obviously f satisfies F_1) and F_2) , therefore by Lemma 2.2 , there exists a con $C > 0$ (independent upon σ) such that $\|u\|_4$ is bounded by $C(1 + |g|)$. In virtue of the classical Leray-Schauder fixed point theorem , we deduce that T has at least one fixed point which solves (1.1)-(1.3) .The proof is therefore complete.

Theorem 3.2 We assume that f satisfies F_1) and F_2). Then for every $\alpha \in R^1$, there exists a dense open set $G \subset \dot{H} = \dot{L}^2(\Omega)$ such that

- 1) for every $g \in G, S(g, \alpha)$ is finite;
- 2) for every connected component G_β of G , the number of points of $S(g, \alpha)$ for $g \in G_\beta$ is constant.

Proof We will employ some technics used by Fioas and Temam [7]. Denote by $S(g, \alpha)$ the set of solutions of (3.1). It is clear that

$$S(g, \alpha) = S(g, \alpha) - \alpha = \{u - \alpha | u \in S(g, \alpha)\}$$

To prove Theorem 3.2 ,it is sufficient and convenient for us to consider the set $S(g, \alpha)$.

i) Let $F : \dot{V}_4 \rightarrow \dot{L}^2(\Omega)$ as follows

$$F(u) = \Delta^2 u - \Delta f(u + \alpha), \text{ for } u \in \dot{V}_4.$$

Then $F \in C^1$ and

$$F'(u)U = \Delta^2 U - \Delta(f'(u + \alpha)U), \forall U \in \dot{V}_4$$

It is easily seen that the linear operator $K : \dot{V}_4 \rightarrow \dot{L}^2(\Omega)$ defined by

$$KU = -\Delta(f'(u + \alpha)U), \forall U \in \dot{V}_4$$

is compact . Since Δ^2 is an isomorphism from \dot{V}_4 to $\dot{L}^2(\Omega)$, we conclude that $F'(u)$ is a Fredholm operator of index 0 . We infer from the infinite dimensional version of Sard's theorem (see Th. A in [7]) that the set G of regular values g of F is dense

in $\dot{L}^2(\Omega)$, and $S(g, \alpha)$ is discrete in \dot{V}_4 for all $g \in G$ (α is given fixed). Since $S(g, \alpha)$ is compact in \dot{V}_4 , this set is finite.

ii) The second step of the proof consists in showing that G is open.

Let $g_i \in \dot{L}^2(\Omega) - G (i = 1, 2, \dots)$ be a sequence converging in \dot{V}_4 to some limit g . We will prove that $g \in \dot{L}^2(\Omega) - G$. Let $u_i \in S(g_i, \alpha)$, we assume that $F'(u_i)$ is not surjective .

Since

$$\dim \ker F'(u_i) = \dim \text{coker } F'(u_i) > 0 \quad (3.5)$$

there exists $v_i \in V_4, \|v_i\|_4 = 1$, such that $F'(u_i)v_i = 0$ i.e.,

$$\Delta^2 v_i - \Delta(f'(u_i + \alpha)v_i) = 0 \quad (3.6)$$

Since $\{g_i\}$ is bounded in $L^2(\Omega)$, in virtue of the a priori estimate obtained in Section 2 , we know that $\{u_i\}$ is bounded in \dot{V}_4 .

The above properties of $\{u_i\}$ and $\{v_i\}$ enables us to extract subsequences (still denoted by $\{u_i\}$ and $\{v_i\}$) such that

$$u_i \rightarrow u, v_i \rightarrow v \text{ weakly in } \dot{V}_4 \quad (3.7)$$

Since $H^4(\Omega) \subset C^2(\bar{\Omega})$, we deduce by (3.7) that $u_i \rightarrow u, v_i \rightarrow v$ in $C^2(\bar{\Omega})$, Now we can pass to the limit in (3.6) and $\Delta^2 u_i - \Delta f'(u_i + \alpha) = g_i$, we have $\Delta^2 u - \Delta f(u + \alpha) = g ; \Delta^2 v - \Delta(f'(u + \alpha)v) = 0$ i.e. , $u \in S(g, \alpha)$ and $v \in \ker F'(u)$. Since $\|v_i\|_4 = 1, v \neq 0$. Recalling that $F'(u)$ is a Fredholm operator of index 0, we conclude that u is a critical point of F . Therefore

$$g \in \dot{L}^2(\Omega) - G$$

iii) Let $G_1, G_2, \dots, G_j, \dots$ be the connected components of G (G_i is open), and let g_0, g_1 be two points in G_j for same j . Let $u_0 \in F^{-1}(g_0) = S(g_0, \alpha)$. Since G_j is connected, There exists a continuous curve $g(t) : [0, 1] \rightarrow G_j$ such that $g(0) = g_0, g(1) = g_1$ and the implicit function theorem implies that there exists a unique curve $u(t)$ which satisfies

$$F(u(t)) = g(t), u(0) = u_0.$$

Since $g(t)$ is a regular value for every $t \in [0, 1], u(t)$ is defined on the whole interval $[0, 1]$, therefore

$u(1) \in F^{-1}(g_1) = S(g_1, \alpha)$, Such a curve can be constructed from any point $u_k \in S(g_0, \alpha)$. Also two different curves cannot reach the same point u_* of $S(g_1, \alpha)$, Otherwise this would be contradicts to the implicit function theorem around u_* .

Hence there are at least as many points in $S(g_1, \alpha)$ as in $S(g_0, \alpha)$. By symmetry the number of the points in $S(g_0, \alpha)$ and that of the point in $S(g_1, \alpha)$ are the same.

Let $S(G_j) = \bigcup_{g \in G_j} S(g, \alpha)$. then we infer from

the above analysis that $S(G_j)$ can be divided into several parts and each part is a connected component of $S(G_j)$.

Let S_k be such a part of $S(G_j)$. then it is easily seen that the restriction of F on S_k is a C^1 differential isomorphism from S_k to G_j .

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