

Design Of Oil Pipeline Intrusion Monitoring System With Gsm Module-Based Remote Flow Valve Activation Mechanism

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Abstract— In this paper, the design of oil pipeline intrusion monitoring system with GSM module-based remote flow valve activation mechanism is presented. The essence of the system is to detect when there is leakage or leakages in the oil pipeline and to alert the control personnel who sends appropriate control command to close the flow valve in the system. The system comprises of the power supply module, the fluid or oil flow and leakage/intrusion sensing and detection mechanism and the GSM 900 module-based remote flow valve switching mechanism. The system is designed to operate in the auto-mode whereby the system does not require to alert the control personnel to issues the command to activate the flow valve but rather the system automatically activates the flow valves in accordance with the intrusion detection signal results. The paper focused on the design of the hardware part of the system which is the platform that will enable the leakage detection algorithms to be implemented. The entire circuit design is modeled in Proteus software and presented along with the model of the circuit showing the two sensors that are used to detect the flow velocity and pressure differentials that will enable the software part of the system to determine when and where leakage has occurred in the pipeline.

Keywords— Oil Pipeline, Leakage Detection, Intrusion Monitoring, GSM Module, Flow Valve, Multiple Leakage, Proteus Software

1. Introduction

Wireless and electronic technologies are the backbone of today's satellite communication, wireless sensor networks, Internet of Things and smart applications [1,2,3, 4,5,6, 7,8,9, 10,11, 12,13,14,15,16,17,18,19,20,21,22,23,24,25]. Despite the challenges of propagation loss and other

associated losses that wireless signals are subjected to, designers have developed numerous ways to accommodate those losses and still deliver reliable quality of service [26, 27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45, 46]. Hence, nowadays, remote monitoring and protection of essential facilities can be conveniently implemented using various forms of embedded systems and Internet of Things (IoT) or wireless sensor network [47,48,49,50].

Basically, the embedded system with requisite sensors and actuators can be used both for monitoring and remote control of the target facility while the wireless network or IoT setup can be used to provide connection for remote access, data collection, communication and control of the facility [51,52,53,54]. In this paper, oil pipeline intrusion monitoring system is considered [55,56,57]. Particularly, the wireless technology employed in this study is the GSM technology.

The oil pipeline intrusion monitoring system presented in this paper is a form of data acquisition system with control mechanism for remotely closing the flow valve when intrusion is detected [58,59,60,61]. The intrusion monitoring system is a combination of a microcontroller-based electronic device with GSM module that enable the intrusion detection signal to be communicated to a remote control personnel who will issue the command to close the flow valve [62,63,64]. Also, the system can operate in automatic mode whereby the manual control by a control personnel is bypassed. The operations of the system are controlled by the microcontroller based on the program written in line with the desired functionalities and design specifications. Notably, the program development for the system includes the requirement elicitation and analysis phase during which the desired functionalities and design specifications are obtained. Also, the program is coded and loaded into the microcontroller memory from where it is implemented as embedded software.

The detailed design of the oil pipeline intrusion monitoring system is presented. The details include the block diagram showing the key modules that make up the system, the

operating flow diagram of the system, the circuit diagrams, and the description of the various components that are used in the system development. Finally, the description of how the system operates to assist in monitoring pipeline intrusion is presented.

This design of the oil pipeline intrusion monitoring system comprises of the power supply module, the fluid or oil flow and intrusion sensing and detection mechanism and the GSM module-based remote flow valve switching mechanism. The block diagram of the system showing the interconnection of the major modules in the system is presented in Figure1.

2. Methodology

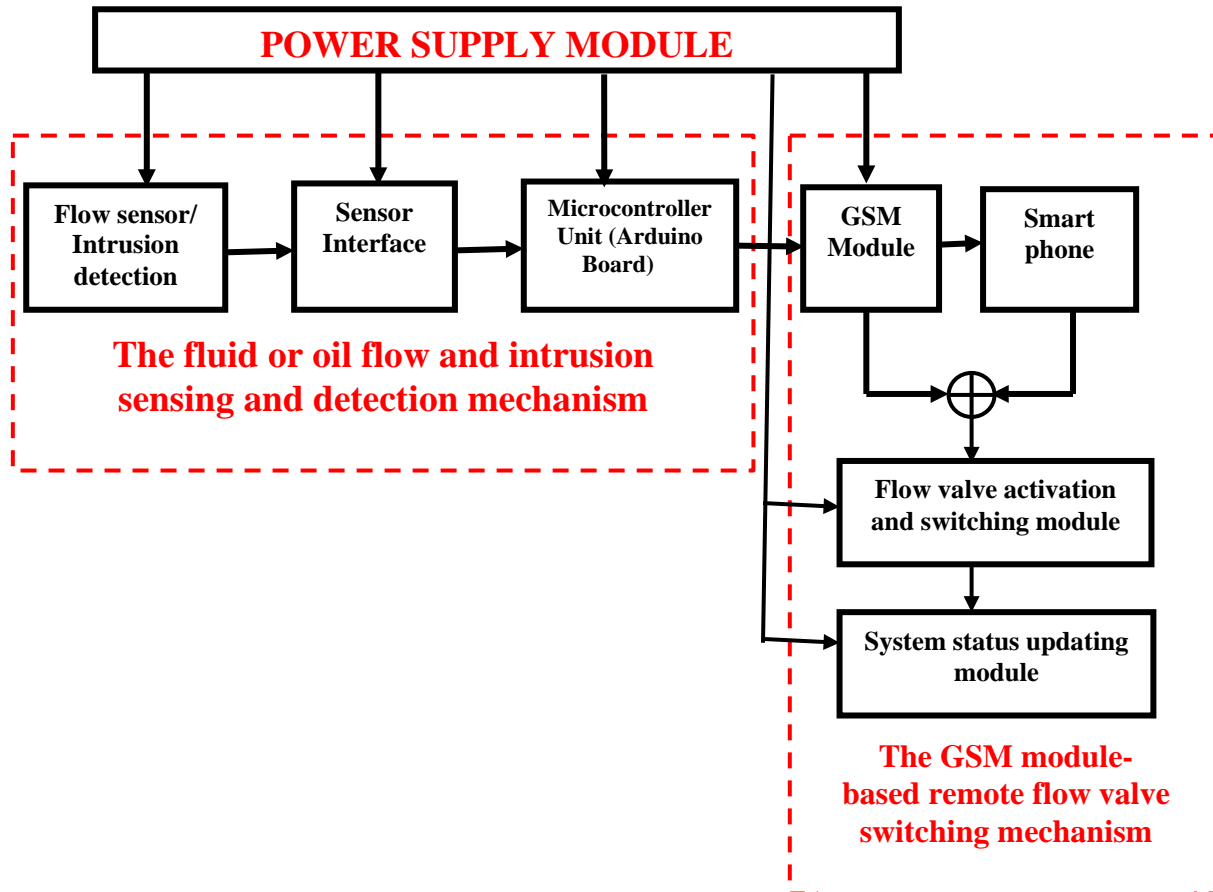


Figure1 The block diagram of the oil pipeline intrusion monitoring system

The system utilizes flow sensors that monitors the drop or difference in the pressure of the oil flowing through the pipeline. The flow sensors are interfaced with a microcontroller, which in this work is Arduino board). When intrusion is sensed by detecting pressure drop, the system response can be an automated valve activation process or a manual valve activation process. In the manual valve activation procedure, when intrusion is sensed, alert signals is sent to a dedicated GSM smartphone in the form of call to the control engineer, who activates the valve switching system. On the other hand, in the automatic valve activation procedure, the intrusion signal is sent directly to the switching control system where the system would be automatically switched off. When this occurs flow valves are shut down. As such, there will be no flow of fluid along the region of intrusion; while the system status is updated in the central control panel for further action by the system

operators. The flow diagram of the procedure used in the oil pipeline intrusion monitoring system for the detection of intrusion and control of the pipeline flow valves is presented in Figure 2.

The switching subsystem consist of the Arduino target board-based switching controller and the GSM module, as shown in the block diagram of Figure 3. Specifically, through the Arduino target board-based switching controller, appropriate signal that corresponds to a command for an SMS that indicate OPEN VALVE or CLOSE VALVE is generated and subsequently switching action is taken by the system to either close or open the flow valves based on the GSM module interpretation of the switching signal from the Arduino target board-based switching controller output.

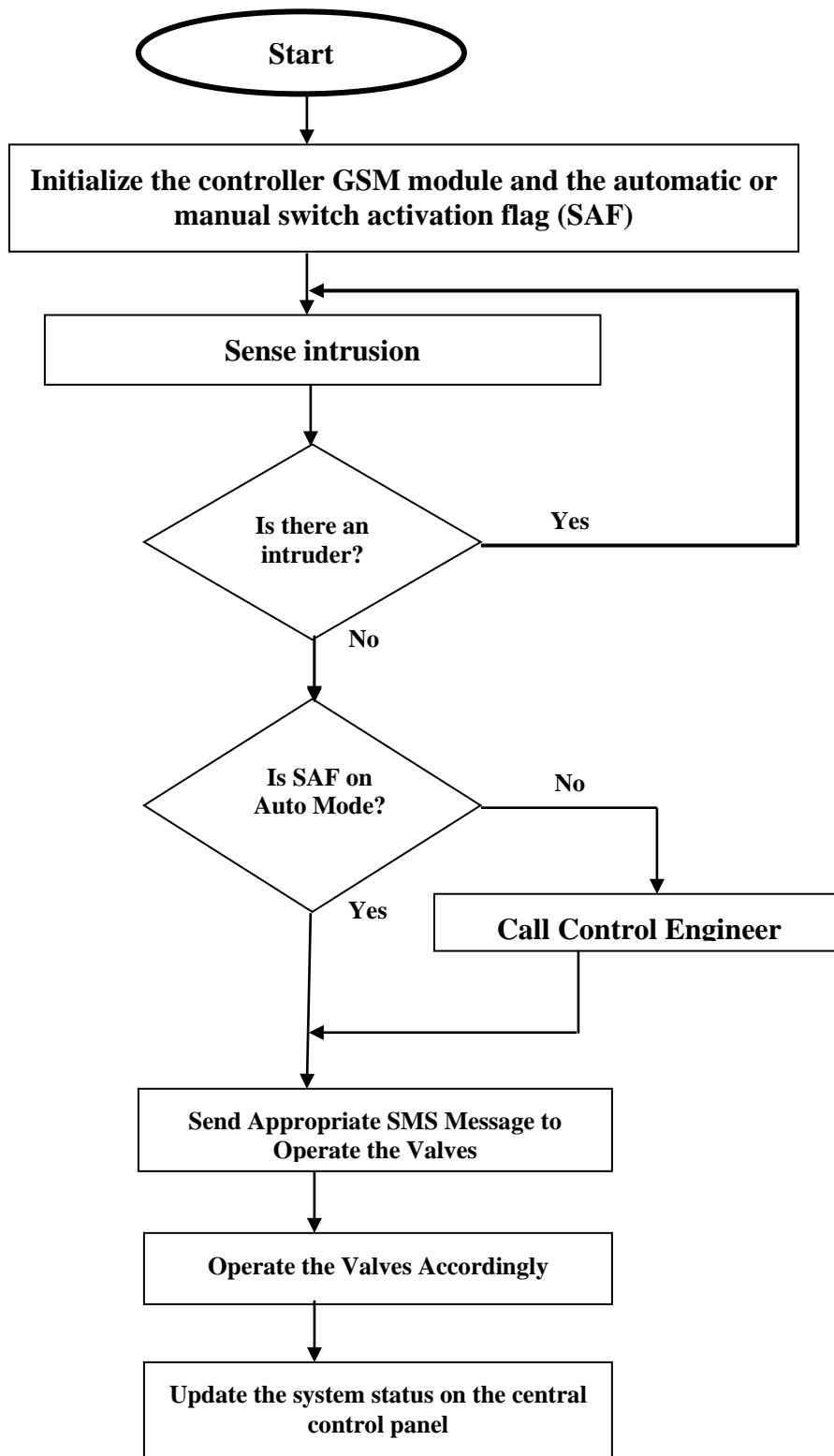


Figure 2 The flow diagram of the procedure used in the oil pipeline intrusion monitoring system for the detection of intrusion and control of the pipeline flow valves

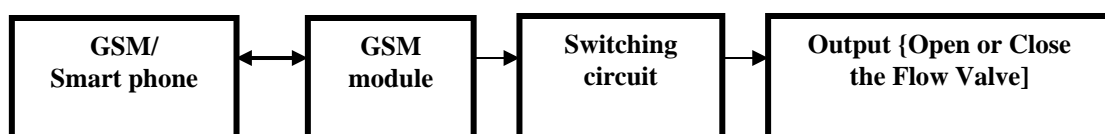


Figure 3 Block diagram of the switching subsystem

The major materials used in the system design are in modules and they include: the power supply module, the power sensor module, the flow sensors, Arduino Target board module and the GSM (Global System for Mobile Communications) Module. It is assumed that the flow valves part of the oil pipeline system and it has its relays which are only turned on or off by the control signal that originates from the oil pipeline intrusion monitoring system. Proteus software was used to model circuit of the system and its operations.

Power Supply Module: The system power is derived from either a battery or the mains power source. In each case, voltage regulator is included to maintain the supply voltage to the circuits at a safe value appropriate for the various components in the system. A 12V, 1.3Ah battery is used. For the voltage regulator, the 180 KHz fixed frequency XL4015 PWM buck (step-down) DC/DC converter IC is used. It can efficiently drive a 5A load with, low ripple and very good line and load regulation. It requires DC input range of 3V-35V and it gives DC output range of 5V

Power Sensor Module: The power sensor module is designed to produce 5V output which is used to represent logic 1. The module is responsible for differentiating when

the system is powered from mains supply or from battery supply.

The Flow Sensors: In this work two flow sensors which are referred to as sensor A and B are used and they placed at the two ends of the flow pipeline. Notably, sensor A monitors the pipeline inflow pressure while sensor B monitors the pipeline outflow pressure. The pressure differential in the two sensors activates the sensors as intrusion detected which in turn cause the signal to be passed to the GSM module. At this point the system response depends on whether the automatic response flag otherwise known as the **switch activation flag (SAF)** is set, in which case the system automatically send the flow valve control signal via the GSM module to the flow valve switching subsystem. If on the other hand the SAF is not set, the manual response is used in which case the system sends a call across to the control personnel who sends the appropriate switching signal via the GSM module to the flow valve switching subsystem.

Arduino Uno Module : The Arduino Uno which is a popular and versatile microcontroller board that is based on the ATmega328 technology. It is used in the design to provide the overall control of the entire system modules. The image of an Arduino Uno module is shown in Figure 4.

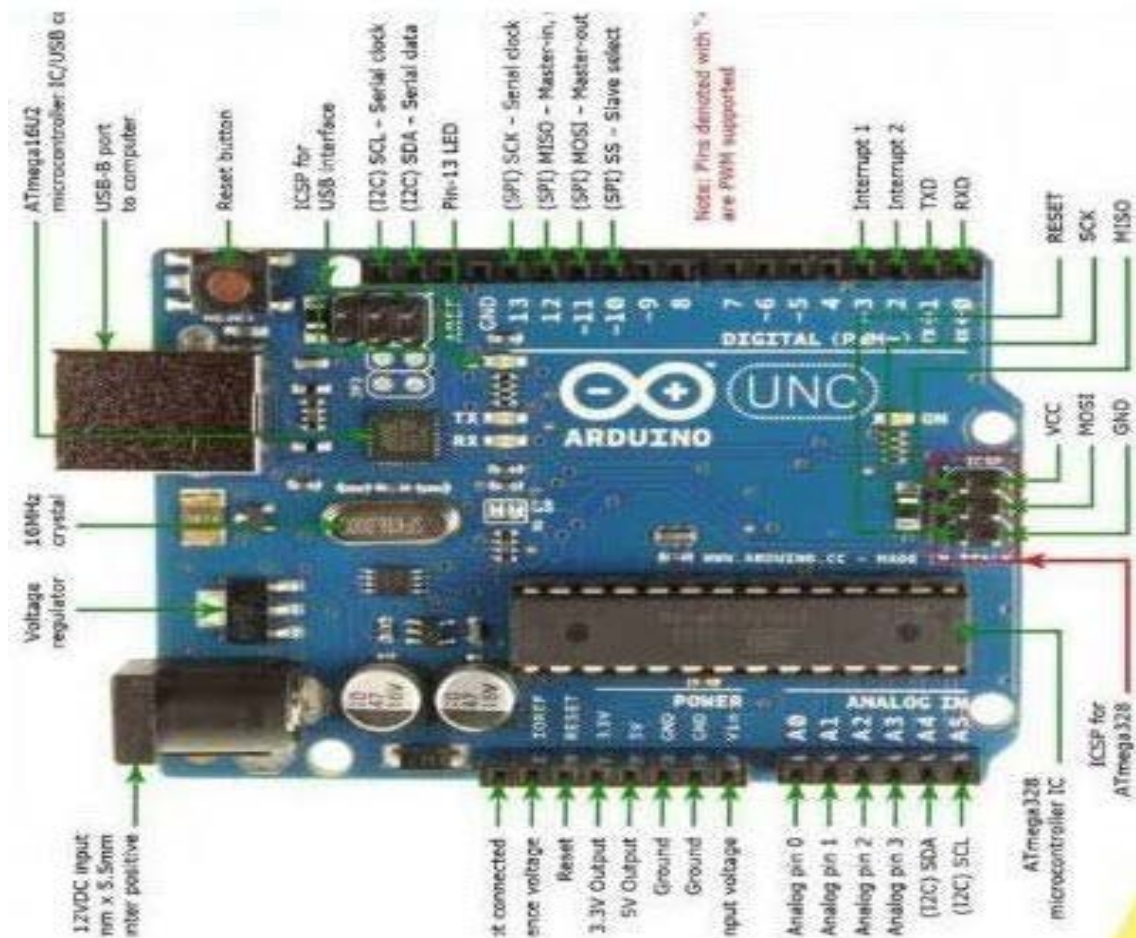


Figure 4 Image of an Arduino Uno Module

GSM Module : The SIM (Subscriber Identity Module) 900 is the GSM interface that is used in the design to allow the system to communicate with the remote receiver system (which in this design is a cell phone of the control

engineer). The image of the GSM Module is shown in Figure 5. The GSM module is interfaced with the Arduino board via the Arduino board serial interface.



Figure 5 The image of the GSM Module

3. Results and Discussions

Proteus 8.4 was used for the purpose of simulation of the designed system. The Proteus software has repository of the requisite components of the systems and the ability to

simulate the flow intrusion and detection scenarios. The diagram of the Proteus software modeled circuit for the GSM module-based remote flow valve switching unit connected to the solenoid valve is shown in Figure 6. The circuit diagram in Figure 6 shows the GSM SIM 900 (labeled GSM 2) interfaced with the Arduino Uno board (labeled ARD 2) as well as the bridge rectifier-based AC to DC converter consisting of the bridge rectifier (labeled BR1), the transformer (labeled TR1), the smoothing capacitor (labeled C3) and the three pin voltage regulator IC (labeled U2) with the three pins labeled as VI, VO and GND. The circuit diagram also shows the solenoid valve relay (labeled RL1) with the a 12 V switching transistor (labeled Q1) along with the transistor base driver 1k Ω resistor R3 connect from the Arduino board to the solenoid valve relay.

As stated earlier, in this work two flow sensors which are referred to as sensor A and B are used and they placed at the two ends of the flow pipeline. Notably, sensor A monitors the pipeline inflow pressure while sensor B monitors the pipeline outflow pressure. The two flow sensors are modeled in the Proteus software as flow measurement terminal 1 and flow measurement terminal 2 and their corresponding circuit diagrams, as modelled in the Proteus software are shown in Figure 7 and figure 8 respectively.

Figure 6 The circuit diagram of the GSM module-based remote flow valve switching unit connected to the solenoid valve

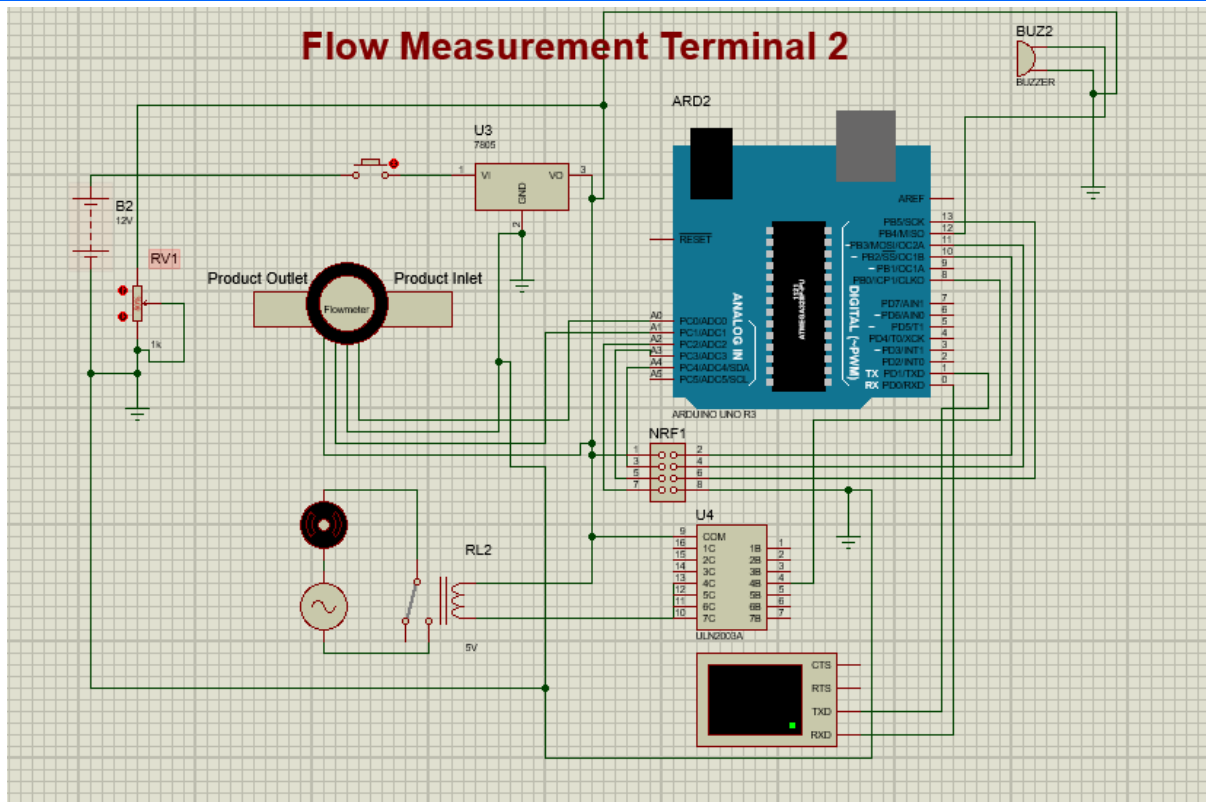


Figure 7 The circuit diagram of the flow sensor A referred to as flow measurement terminal 1 in the Proteus software model of the system

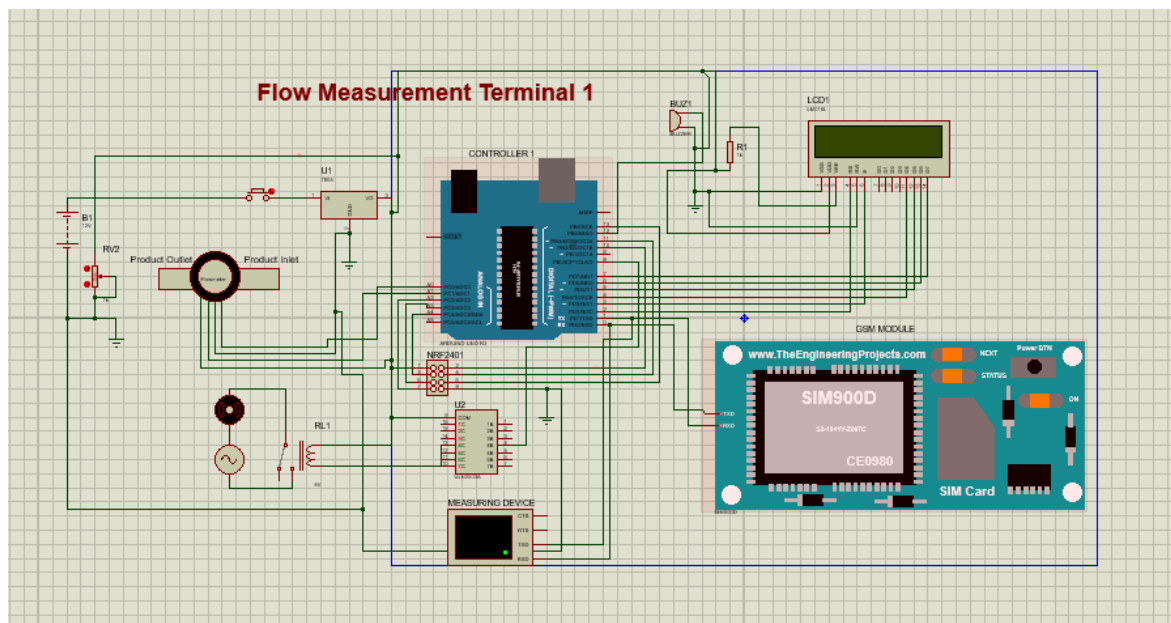


Figure 8 The circuit diagram of the flow sensor B referred to as flow measurement terminal 2 in the Proteus software model of the system

4 Conclusion

The design of the hardware component of an oil pipeline intrusion monitoring system is presented. The hardware is part of an oil pipeline intrusion detection system which requires some analytical model to run on top of the hardware components to detect the occurrence of leakage or leakages in the pipeline and hence trigger a response sequence that can lead to closure of the flow valve in the

pipeline and hence stop further leakage or stop the intruder from further stealing of the oil through the leakage points. The system is designed using Arduino microcontroller board and GSM 900 module for communicating the oil leakage status and flow valve activation commands in accordance to the system design specifications. The entire circuit components, the components connections and system operations are modeled and simulated in Proteus software.

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