Numerical Simulation Of Three-Dimensional Turbulent Reacting Gas Jets Arising Nozzle Rectangular Based "K-ε" Turbulence Models.

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Abstract—The main tool for the study of gas dynamics, heat and mass transfer of turbulent jet flows of multi component gas mixtures is mathematical modeling, which in contrast to the physical experiment is often more cost-effective and often the only possible method of research. In general, the simulation of turbulent jet flows of the reacting gas mixtures based on the common system of coupled partial differential equations that express the laws of conservation of mass, momentum, energy and mass.

Keywords—Turbulence	models,	arising
nozzle, gas dynamics.		

<u>Introduction.</u> In $[1 \div 9]$ presents mainly the results of experimental and theoretical - numerical calculations devoted to research flow of air flowing from the nozzle of rectangular shape.

In this paper the method of calculation and some numerical results of the study of threedimensional turbulent reacting gas jets emanating from the nozzle of rectangular shape.

Problem Statement. Consider reactive streams flowing from the nozzle of rectangular shape and extending wake (flooded) air flow. As the origin of the Cartesian system we choose the center of the initial section of the jet: the x-axis is directed along the jet and the axis OY and OZ parallel to the sides of the nozzle and the size respectively. Suppose that for symmetric about the axis OX and planes YOX, ZOX, which form the boundary of the domain of integration and that allow us to consider only one-quarter of the rectangular jet.

This flow is described by the following system of equations paralyzed [7 ÷11]:

$$\begin{aligned} \frac{\partial\rho u}{\partial x} + \frac{\partial\rho v}{\partial y} + \frac{\partial\rho w}{\partial z} &= 0, \end{aligned} \tag{1}$$

$$\rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial u}{\partial y} + \rho w \frac{\partial u}{\partial z} &= -\frac{\partial P}{\partial x} + \frac{\partial}{\partial y} (\mu_T \frac{\partial u}{\partial y}) + \frac{\partial}{\partial z} (\mu_T \frac{\partial u}{\partial z}), \end{aligned} \tag{2}$$

$$\rho u \frac{\partial v}{\partial x} + \rho v \frac{\partial v}{\partial y} + \rho w \frac{\partial v}{\partial z} &= -\frac{\partial P}{\partial y} + \frac{4}{3} \frac{\partial}{\partial y} (\mu_T \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T \frac{\partial v}{\partial z}) - \frac{2}{3} \frac{\partial}{\partial y} (\mu_T \frac{\partial w}{\partial z}) + \frac{\partial}{\partial z} (\mu_T \frac{\partial w}{\partial y}), \end{aligned} \tag{3}$$

$$\rho u \frac{\partial w}{\partial x} + \rho v \frac{\partial w}{\partial y} + \rho w \frac{\partial w}{\partial z} &= -\frac{\partial P}{\partial z} + \frac{4}{3} \frac{\partial}{\partial z} (\mu_T \frac{\partial w}{\partial z}) + \frac{\partial}{\partial y} (\mu_T \frac{\partial w}{\partial y}) + \frac{\partial}{\partial y} (\mu_T \frac{\partial v}{\partial z}) - \frac{2}{3} \frac{\partial}{\partial y} (\mu_T \frac{\partial v}{\partial z}) - \frac{2}{3} \frac{\partial}{\partial z} (\mu_T \frac{\partial v}{\partial y}), \end{aligned} \tag{4}$$

$$\rho u \frac{\partial W}{\partial x} + \rho v \frac{\partial W}{\partial y} + \rho w \frac{\partial H}{\partial z} &= -\frac{\partial}{\partial z} + \frac{4}{3} \frac{\partial}{\partial z} (\mu_T \frac{\partial W}{\partial z}) + \frac{\partial}{\partial y} (\mu_T \frac{\partial W}{\partial y}) + \frac{\partial}{\partial y} (\mu_T \frac{\partial v}{\partial z}) - \frac{2}{3} \frac{\partial}{\partial z} (\mu_T \frac{\partial v}{\partial y}), \end{aligned} \tag{4}$$

$$\rho u \frac{\partial H}{\partial x} + \rho v \frac{\partial H}{\partial y} + \rho w \frac{\partial H}{\partial z} &= \frac{1}{\Pr_T} \frac{\partial}{\partial y} (\mu_T \frac{\partial H}{\partial y}) + \frac{1}{\Pr_T} \frac{\partial}{\partial z} (\mu_T \frac{\partial H}{\partial z}) + (1 - \frac{1}{\Pr_T}) [\frac{\partial}{\partial y} (\mu_T w \frac{\partial u}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial w}{\partial z})] - \end{aligned} \tag{5}$$

$$- \frac{\partial}{\partial y} (\frac{2}{3} \mu_T v \frac{\partial w}{\partial z}) + \frac{\partial}{\partial z} (\mu_T v \frac{\partial w}{\partial y}) + \frac{\partial}{\partial y} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T v \frac{\partial w}{\partial z}) + \frac{\partial}{\partial y} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) - \frac{\partial}{\partial z} (\frac{2}{3} \mu_T w \frac{\partial v}{\partial y}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}) + \frac{\partial}{\partial z} (\mu_T w \frac{\partial v}{\partial z}$$

$$\rho u \frac{\partial \varepsilon}{\partial x} + \rho v \frac{\partial \varepsilon}{\partial y} + \rho w \frac{\partial \varepsilon}{\partial z} = \frac{\partial}{\partial y} \left(\frac{\mu_T}{\sigma_{\varepsilon}} \frac{\partial \varepsilon}{\partial y} \right) + \frac{\partial}{\partial z} \left(\frac{\mu_T}{\sigma_{\varepsilon}} \frac{\partial \varepsilon}{\partial z} \right) + C_{\varepsilon 1} G - C_{\varepsilon 2} \rho \varepsilon \left(\frac{\varepsilon}{k} \right) \frac{\varepsilon}{k}, \tag{8}$$

где
$$G = \mu_T \left[\left(\frac{\partial u}{\partial y} \right)^2 + \left(\frac{\partial u}{\partial z} \right)^2 \right]$$

 $H = c_p T + \frac{u^2 + v^2 + w^2}{2} + \sum_{i=1}^{N_k} C_i h_i^*$
 $P = \rho T R \sum_{i=1}^{N_k} \frac{C_i}{m_i}$
 $\mu_T = \frac{C_\mu \rho k^2}{\varepsilon}$

In equation (1÷11) x, y, z - Cartesian coordinates, ρ - density: u, v, w- velocity components; T- temperature; Total enthalpy H, Hpressure; k - turbulent kinetic energy; ε - turbulent kinetic energy dissipation; C_i- the mass concentration; i- the component, N_k- number of components in the mixture; cp- heat capacity at constant pressure; Pr_T, Sc_T - turbulent Prandtl number and Schmidt; h_1^* - heat of formation i – the component ; R – universal gas constant; m_i molecular weight i- the component; w_i - the rate of formation ithe component, as well as $C_{a}, C_{\varepsilon^2}, C_{\mu}, \sigma_k, \sigma_{\varepsilon}$, - empirical constants "k-ε" turbulence model.

In this paper we present an effective method like SIMPLE, direct method to solve the Poisson

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(11)

equation for determining the corrections to the velocity. Allegedly unnecessary continuity equation used to calculate the weight imbalance. In contrast to [11,13] amendment provides for three components of the velocity. The solutions u, v, w the new iteration are expressed as estimated (u_p, v_p, w_p) Plus correction (u_c, v_c, w_c) and they are determined from the continuity equation administration building

Q,
$$pu_c = \frac{\partial Q}{\partial x}$$
, $pv_c = \frac{\partial Q}{L\partial y}$, $pw_c = \frac{\partial Q}{\partial z}$ which is

the solution of the Poisson equation:

$$\frac{\partial^2 \mathbf{Q}}{\partial x^2} + \frac{\partial^2 \mathbf{Q}}{L^2 \partial y^2} + \frac{\partial^2 \mathbf{Q}}{\partial z^2} = Q_p \qquad (12)$$

where Q_P – source term.

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